

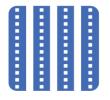
Politecnico di Torino Interdepartmental Centre for Service Robotics

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Centre Coordinator





SMART CITY SEARCH & RESCUE



SERVICE ROBOTICS FOR WELLBEING



CULTURAL HERITAGE



UNDERWATER





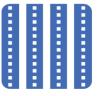
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PICfSeR o r

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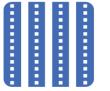
PIC4SeR

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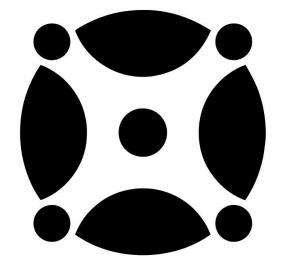








PIC4SeR

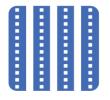


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PIC4SeR - Service robotics

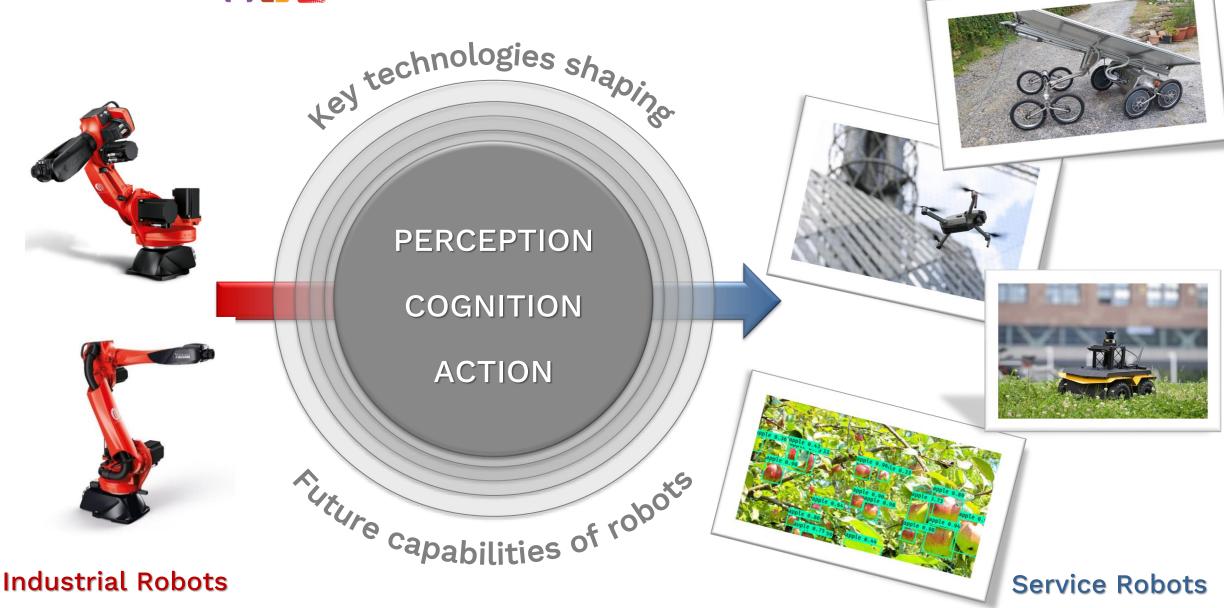
Service robots assist human beings, typically by performing a job that is dirty, dull, distant, dangerous or repetitive, including household-chores. They typically are autonomous and/or operated by a built-in control system, with manual override options. The term "service robot" does not have a strict technical definition. The International Organization for Standardization defines a "service robot" as a robot "that performs useful tasks for humans or equipment excluding industrial automation applications"







PIC4SeR - Service robotics



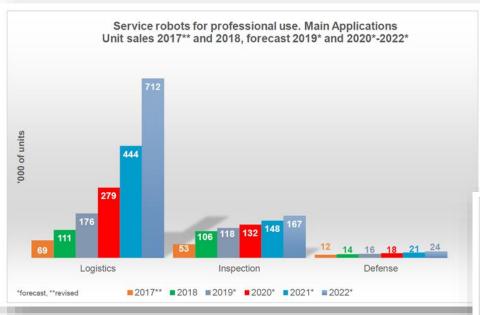


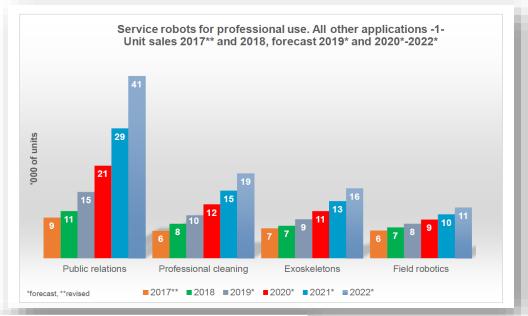


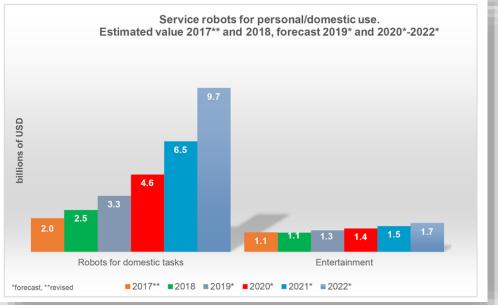


PIC4SeR - Reference market

IFR (International Federation of Robotics) "World Robotics 2019 – Service Robots"













PIC4SeR - Why?

- Many of the current research, innovation and development in the service robotic field, can be classified as disruptive technologies
- Several uncorrelated research projects and industrial partnerships must be harmonized and coordinated to optimize the results
- To start a common workplace, a common knowledge and a common language
- To develop an integrated approach and technology development process in this booming area
- To help PoliTO reaching a critical mass in this sector (instead of several scattered initiatives)
- To link together technology needs coming from several industrial partners
- To start interdisciplinary didactic activities in this area
- To join several international research communities with a unique "face" and coordinated research proposals









PIC4SeR in pills

5 PoliTO departments

- DET (Electronics & Telecoms)
- DAUIN (Informatics & Control)
- **DIMEAS (Mechanics & Aerospace)**
- DIATI (Geomatics & Photogrammetry)
- DAD (Design & Cultural Heritage)

50 people involved

- 21 staff
- 12 researcher
- 17 PhD students

Location: c/o COVIVIO building

- C.so Ferrucci 112 Torino
- 580mq of labs and offices
- indoor & outdoor facilities available for testing







PIC4SeR - Enabling technologies

GNSS navigation /Energy optimization 4G and 5G Networks Cooperative positioning /Path planning **Sensor** integration **SDR** receivers Soft robotics **Locomotion** platforms /Multimedia communication ROS2 **Control Coding Human Machine Interaction** Internet of Things **Machine Learning** Interaction visualitazion **Artificial Intelligence** Data fusion /Interaction design /System Co-Design /Edge-Fog-Cloud Computing **Ethics** Co-living Design **Embedded** Computing







PIC4SeR – key application areas











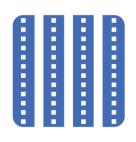




PIC4SeR – key application areas







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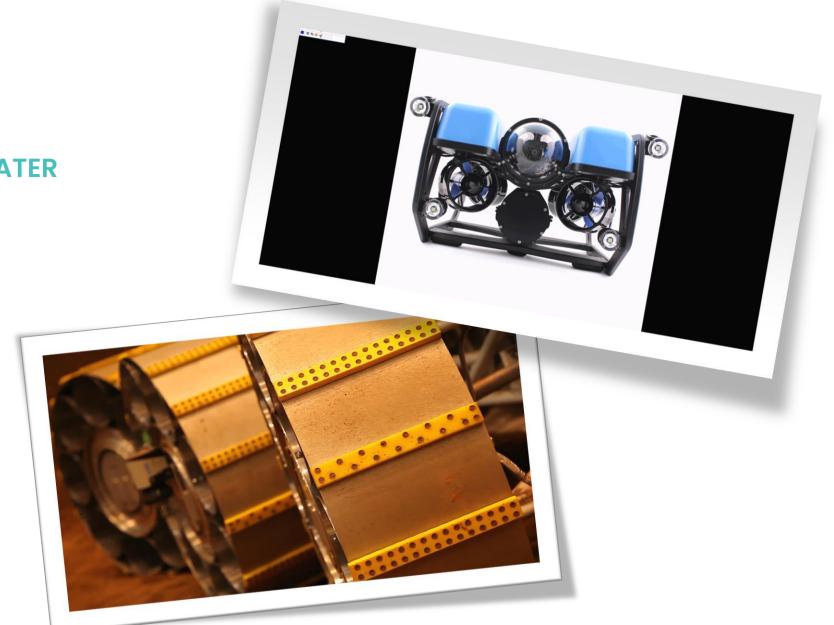


PIC4SeR – key application areas















PIC4SeR – Internal organization

PLATFORMS TECHNOLOGIES Local/Global Mechanism **AUV & ROV** AI & ML **UGV UAV Electronics Positioning** design Applications Energy Generalization Core Core Core management Locomotion **GNSS** Perception platforms **Embedded** (CV) systems SLAM **SLAM Navigation Projects** RL System Vision / Image architecture Planning **UWB** Robotic arms processing Planning **Planning** Power Indoor/ Edge Al electronics Outdoor







Companies & Research partners























European Space Agency



























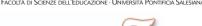


































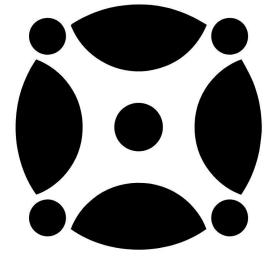
SCAN ME







Thank you



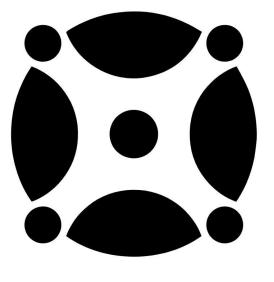
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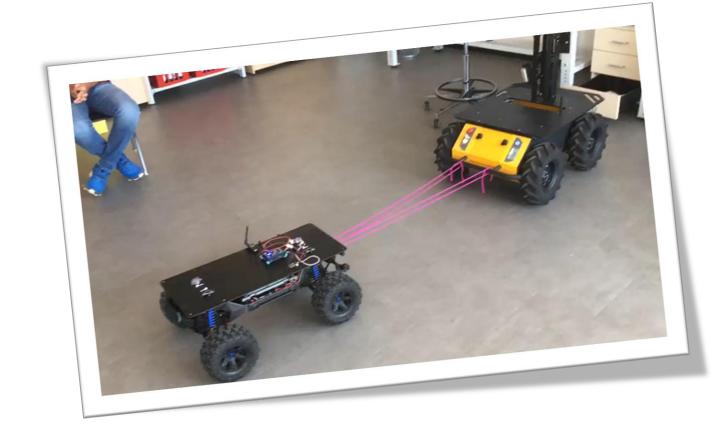






Thank you





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